# WORLD-BEAM QS18U Ultrasonic Sensors

Miniature Ultrasonic Sensors with TEACH-Mode Programming





Features

- · Fast, easy-to-use TEACH-Mode programming; no potentiometer adjustments
- Ultra-compact housing
- One discrete output: NPN or PNP, depending on model
- Two bi-colored status LEDs
- · Rugged encapsulated version for harsh environments
- Choose 2 meter or 9 meter unterminated cable, 4-pin Euro-style or 4-pin Pico-style QD connectors (either integral or with 150 mm pigtail)
- Wide operating range of -20° to +60° C (-13° to +140° F)
- Temperature compensation
- · Configurable for normally open or normally closed operation
- Fast response time (15 milliseconds)

### Models

Models	Sensing Range	TEACH Option	Cable	Supply Voltage	Output
QS18UNA QS18UPA QS18UNAE QS18UPAE	50 mm to 500 mm (2 in to 20 in)	Integral push button or remote TEACH (IP67, NEMA 6P) Remote TEACH (epoxy-encapsula- ted, IP68, NEMA 6P)	4-wire, 2 m (6.5 ft) cable with shield	12-30V dc	NPN PNP NPN PNP

Only standard 2 m (6.5 ft) cable models are listed. For 9 m (30 ft) shielded cable, add suffix "W/30" to the model number (e.g., QS18UNA W/30). A model with a QD connector requires a mating cordset. For QD models:

- For 4-pin integral Euro-style QD, add suffix "Q8" (e.g., QS18UNAQ8).
- For 4-pin Euro-style 150 mm (6") pigtail QD, add suffix "Q5" (e.g., QS18UNAQ5).
- For 4-pin integral Pico-style QD, add suffix "Q7" (e.g., QS18UNAQ7).
- For 4-pin Pico-style 150 mm (6") pigtail QD, add suffix "Q" (e.g., QS18UNAQ).



#### WARNING: Not To Be Used for Personnel Protection

Never use this device as a sensing device for personnel protection. Doing so could lead to serious injury or death. This device does not include the self-checking redundant circuitry necessary to allow its use in personnel safety applications. A sensor failure or malfunction can cause either an energized or deenergized sensor output condition.



### **Principles of Operation**

Ultrasonic sensors emit one or multiple pulses of ultrasonic energy, which travel through the air at the speed of sound. A portion of this energy reflects off the target and travels back to the sensor. The sensor measures the total time required for the energy to reach the target and return to the sensor. The distance to the object is then calculated using the following formula:  $D = ct \div 2$ 

**D** = distance from the sensor to the target

c = speed of sound in air

t = transit time for the ultrasonic pulse

To improve accuracy, an ultrasonic sensor may average the results of several pulses before outputting a new value.

### **Temperature Effects**

The speed of sound is dependent upon the composition, pressure and temperature of the gas in which it is traveling. For most ultrasonic applications, the composition and pressure of the gas are relatively fixed, while the temperature may fluctuate.

In air, the speed of sound varies with temperature according to the following approximation:

In metric units:	$C_{m/s} = 20 \sqrt{273 + T_{C}}$	In English units:	$C_{ft/s}$ = 49 $\sqrt{460 + T_F}$
C <sub>m/s</sub> = speed of s	sound in meters per second	C <sub>ft/s</sub> = speed of so	und in feet per second
T <sub>C</sub> = temperature in °C		T <sub>F</sub> = temperature i	n °F

### Temperature Compensation

Changes in air temperature affect the speed of sound, which in turn affects the distance reading measured by the sensor. An increase in air temperature shifts both sensing window limits closer to the sensor. Conversely, a decrease in air temperature shifts both limits farther away from the sensor. This shift is approximately 3.5% of the limit distance for a 20° C change in temperature.

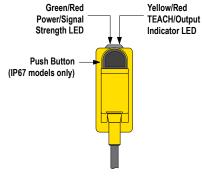
The QS18U series ultrasonic sensors are temperature compensated This reduces the error due to temperature by about 90%. The sensor will maintain its window limits to within 1.8% over the -20° to +60° C (-4° to +140° F) range.

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### NOTE:

- Exposure to direct sunlight can affect the sensor's ability to accurately compensate for changes in temperature.
- If the sensor is measuring across a temperature gradient, the compensation will be less effective.
- The temperature warmup drift upon power-up is less than 7% of the sensing distance. After 5 minutes, the apparent switchpoint will be within 0.6% of the actual position. After 25 minutes, the sensing position will be stable.

### Sensor Programming



Two TEACH methods may be used to program the sensor:

- · Teach individual minimum and maximum limits, or
- Use Auto-Window feature to center a sensing window around the taught position

The sensor may be programmed either via its push button, or via a remote switch. Remote programming also may be used to disable the push button, preventing unauthorized personnel from adjusting the programming settings. To access this feature, connect the white wire of the sensor to 0V dc, with a remote programming switch between the sensor and the voltage.

Figure 1. Sensor Features

Programming is accomplished by following the sequence of input pulses (see *programming procedures*). The duration of each pulse (corresponding to a push button "click"), and the period between multiple pulses, are defined as "**T: 0.04 seconds < T < 0.8 seconds.**"

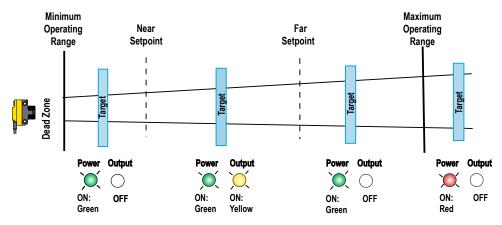


Figure 2. TEACH Interface

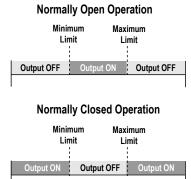
### **Status Indicators**

Power ON/OFF LED	Indicates	Output/Teach LED	Indicates
OFF	Power is OFF	OFF	Target is outside window limits (normally open opera- tion).
ON Red	Target is weak or outside sensing range.	Yellow	Target is within window limits (normally open opera- ton).
ON Green	Sensor is operating normally, good target.	ON Red (solid)	In Teach Mode, waiting for first limit.
		ON Red (flashing)	In Teach Mode, waiting for second limit.

### **Teaching Minimum and Maximum Limits**

#### **General Notes on Programming**

- The sensor returns to Run mode if the first TEACH condition is not registered within 120 seconds.
- After the first limit is taught, the sensor remains in Program mode until the TEACH sequence is finished.
- To exit Program mode without saving any changes, press and hold the programming push button for more than 2 seconds (before teaching the second limit). The sensor reverts to the last saved limits.



# Figure 3. Teaching independent minimum and maximum limits

	Proc	Result	
	Push Button (0.04 sec ≤ Click ≤ 0.8 sec)	Remote Line (0.04 sec < T < 0.8 sec)	
Programming Mode	Press and hold push button	No action required; sensor is ready for 1st limit teach	Output LED: ON Red Power LED: ON Green (good signal) or ON Red (no signal)
Teach First	Position the target for the first limit	Position the target for the first limit	Power LED: Must be ON Green
Limit	"Click" the push button	Single-pulse the remote line	Teach Accepted Output LED: Flashing Red Teach Unacceptable Output LED: ON Red
Teach Second	Position the target for the second limit	Position the target for the second limit	Power LED: Must be ON Green
Limit	"Click" the push button	Single-pulse the remote line	Teach Accepted Output LED: Yellow or OFF Teach Unacceptable Output LED: Flashing Red

### **Teaching Limits Using the Auto-Window Feature**

Teaching the same limit twice automatically centers a 20 mm window on the taught position.

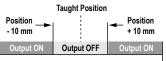
### **General Notes on Programming**

- The sensor returns to Run mode if the first TEACH condition is not registered within 120 seconds.
- After the first limit is taught, the sensor remains in Program mode until the TEACH sequence is finished.
- To exit Program mode without saving any changes, press and hold the programming push button for more than 2 seconds (before teaching the second limit). The sensor reverts to the last saved program.

### Taught Position Position - 10 mm - 10 mm + 10 mm Output OFF Output ON Output OFF

**Normally Open Operation** 

### **Normally Closed Operation**



### Figure 4. Using the Auto-Window feature for programming each output

	Procedure		Result
	Push Button (0.04 sec ≤ Click ≤ 0.8 sec)	Remote Line (0.04 sec < T < 0.8 sec)	
Programming Mode	Press and hold push button	No action required; sensor is ready for 1st limit teach	Output LED: ON Red Power LED: ON Green (good signal) or ON Red (no signal)
Teach First Limit	Position the target for the first limit	Position the target for the center of the window	Power LED: Must be ON Green
	"Click" the push button	Single-pulse the remote line	Teach Accepted Output LED: Flashing Red Teach Unacceptable Output LED: ON Red
Re-Teach Limit	Without moving the target, "click" the push button again	Without moving the target, single-pulse the remote line again	Teach Accepted Output LED: Yellow or OFF Teach Unacceptable Output LED: Flashing Red

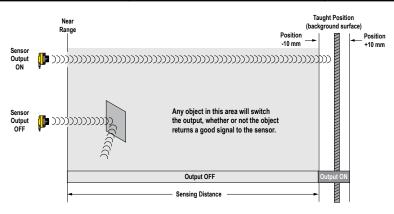


Figure 5. An application for the Auto-Window feature (retroflective mode)

### Normally Open/Normally Closed Operation Select

The sensor can be configured for either normally open or normally closed operation via the remote teach wire (white). A series of three pulses on the line will toggle between normally open (NO) and normally closed (NC) operation. Normally open is defined as the output energizing when the target is present. Normally closed is defined as the output energizing when the target is absent. (See *Figure 3. Teaching independent minimum and maximum limits* on page 4 and *Figure 4. Using the Auto-Window feature for programming each output* on page 5.)

	Р	Result	
	Push Button 0.04 sec ≤ Click ≤ 0.8 sec	Remote Line 0.04 sec < T < 0.8 sec	
Toggle be- tween NO/NC Operation	Not available via push button	Triple-pulse the remote line	Either Normally Open or Normally Closed operation is selected, depend- ing on previous condition.

### Push Button Lockout

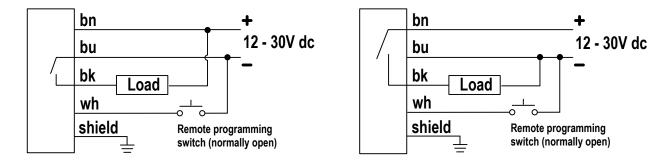
Enables or disables the push button to prevent unauthorized personnel from adjusting the program settings.

	Proce	Result	
	Push Button 0.04 seconds ≤ "Click" ≤ 0.8 seconds	Remote Line 0.04 sec < T < 0.8 sec	
Push Button Lockout	<ul> <li>Not available via push but- ton</li> </ul>	• Four-pulse the remote line T $T$ $T$ $T$ $T$ $T$ $T$ $T$ $T$ $T$	Push buttons are either enabled or disabled, depending on condition.

### Wiring

### NPN (Sinking) Output Models

#### PNP (Sourcing) Output Models



### Cable and QD hookups are functionally identical.

It is recommended that the shield wire be connected to earth ground. Shielded cordsets are recommended for all QD models.

### **Specifications**

### Sensing Range

50 to 500 mm (2 to 20 inches)

### Supply Voltage

12 - 30V dc (10% maximum ripple); 25 mA max (exclusive of load)

### Ultrasonic Frequency

300 kHz, rep. rate 7.5 ms

### **Supply Protection Circuitry**

Protected against reverse polarity and transient voltages

### **Output Configuration**

SPST solid-state switch conducts when target is sensed within sensing window; one NPN (current sinking) or one PNP (current sourcing), depending on model.

### **Output Protection**

Protected against short-circuit conditions

### **Output Rating**

**Rating:** 100 mA maximum load; see Application Note 1 **Off-state leakage current:** less than 10  $\mu$ A (sourcing); less than 200  $\mu$ A (sinking); see Application Note 2 **ON-state saturation voltage:** NPN: less than 1.6V @

100 mA; **PNP**: less than 3.0V @ 100 mA

### Output Response

15 milliseconds

### Delay at Power Up

300 milliseconds

### Temperature Effect

Non-encapsulated models:  $\pm 0.05\%$  per °C from -20 to +50 °C,  $\pm 0.1\%$  per °C from +50 to +60 °C Encapsulated models:  $\pm 0.05\%$  per °C from 0 to +60 °C,  $\pm 0.1\%$  per °C from -20 to 0 °C

### Repeatability

0.7 mm

### **Minimum Window Size**

5 mm

### Hysteresis

1.4 mm

#### Indicators

### Range Indicator (Red/Green) and Teach/Output Indicator (Yellow/Red)

**Range Indicator:** Green - Target is within sensing range; Red - Target is outside sensing range; OFF - Sensing Power is OFF

**Teach/Output Indicator:** Yellow - Target is within taught limits; OFF - Target is outside taught window limits; Red - Sensor is in TEACH mode

### Adjustments

Sensing Window Limits: TEACH-mode programming of near and far window limits may be set using the push button or remotely via TEACH input

### Construction

ABS housing, TPE Push Button, ABS Push Button housing, Polycarbonate lightpipes

### Connections

2 m (6.5 ft) or 9 m (30 ft) 4-conductor PVC jacketed attached cable, or 4-pin Euro-style integral QD (Q8), or 4-pin Pico-style integral QD (Q7), or 4-pin Euro-style 150 mm (6 in) pigtail QD (Q5), or 4-pin Pico-style 150 mm (6 in) pigtail QD (Q)

### **Environmental Rating**

Leakproof design, rated NEMA 6P; IEC IP67 or IP68 depending on model; UL Type 1

### **Operating Conditions**

Temperature: -20 to +60 °C (-4 to +140 °F) Relative Humidity: 100% (non-condensing)

### Vibration and Mechanical Shock

All models meet Mil. Std. 202F requirements method 201A (vibration: 10 to 60 Hz max., double amplitude 0.06", maximum acceleration 10G). Also meets IEC 947-5-2 requirements: 30G 11 ms duration, half sine wave.

#### **Temperature Warmup Drift**

See Temperature Compensation on page 2

#### **Application Notes**

1. If supply voltage is > 24V dc, derate maximum output current 5 mA/°C above 50°C.

2. NPN off-state leakage current is < 200  $\mu$ A for load resistances > 3 k $\Omega$  or optically isolated loads. For load current of 100 mA, leakage is < 1% of load current. 3. Objects passing inside the specified near limit may

### produce a false response.

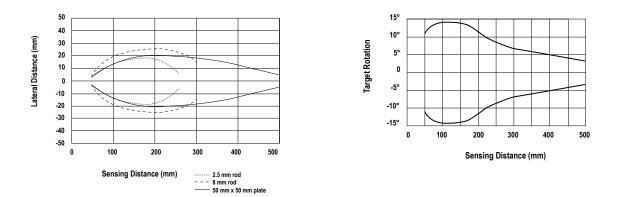
### Certifications

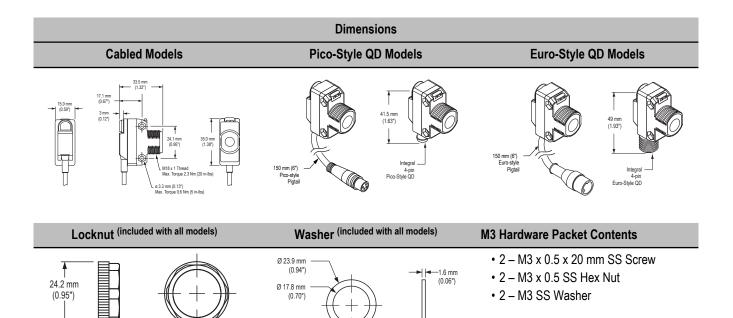


### **QS18U Effective Beam Pattern (Typical)**

-8.0 mm (0.32")

### **QS18U Maximum Target Rotation Angle**





# Quick-Disconnect (QD) Cordsets

4-Pin Snap-On M8/Pico-Style Cordsets with Shield					
Model	Length	Style	Dimensions	Pinout	
PKG4S-2	2.00 m (6.56 ft)	Straight	ø10 mm max	4	
PKW4ZS-2	2.00 m (6.56 ft)	Right Angle	25 mm max. (1.0") 20 mm (0.8") ∞12 mm max. (0.5")	1 = Brown 2 = White 3 = Blue 4 = Black	

4-Pin Threaded M12/Euro-Style Cordsets with Shield					
Model	Length	Style	Dimensions	Pinout	
MQDEC2-406	1.83 m (6 ft)	Straight	<b></b> 44 Typ. <b></b> ►		
MQDEC2-415	4.57 m (15 ft)		M12 x 1 ø 14.5	1-0-2	
MQDEC2-430	9.14 m (30 ft)				
MQDEC2-406RA	1.83 m (6 ft)	Right-Angle	, 32 Typ.	4-00-3	
MQDEC2-415RA	4.57 m (15 ft)		[1.26"] 30 Typ. [1.18"] M12 x 1 ø 14.5 [0.57"]	1 = Brown 2 = White 3 = Blue 4 = Black	
MQDEC2-430RA	9.14 m (30 ft)				

### **Mounting Brackets**

All measurements are listed in millimeters.

### SMB18A

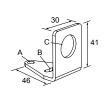
- Right-angle mounting bracket with a curved slot for versatile orientation
- 12-ga. stainless steel
- 18 mm sensor mounting hole
- Clearance for M4 (#8) hardware

**Hole center spacing:** A to B = 24.2 **Hole size:** A =  $\emptyset$  4.6, B = 17.0 × 4.6, C =  $\emptyset$  18.5

### SMB18SF

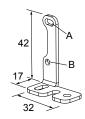
- 18 mm swivel bracket with M18 × 1 internal thread
- · Black thermoplastic polyester
- Stainless steel swivel locking hardware included

Hole center spacing: A = 36.0Hole size:  $A = \emptyset 5.3$ ,  $B = \emptyset 18.0$ 



#### SMBQS18RA

- Right-angle mounting bracket
- 14-ga. 304 stainless steel



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Hole center spacing: A to B=20.3Hole size: A =4.3 × 9.3,  $B=\emptyset$  4.3

### SMB18UR

- 2-piece universal swivel bracket
- · 300 series stainless steel
- Stainless steel swivel locking hardware included
- Mounting hole for 18 mm sensor

Hole center spacing: A = 25.4, B = 46.7 Hole size: B = 6.9 × 32.0, C = ø 18.3

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